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***Module 5***

**TAGUCHI METHOD  
for  
STATIC PROBLEMS**

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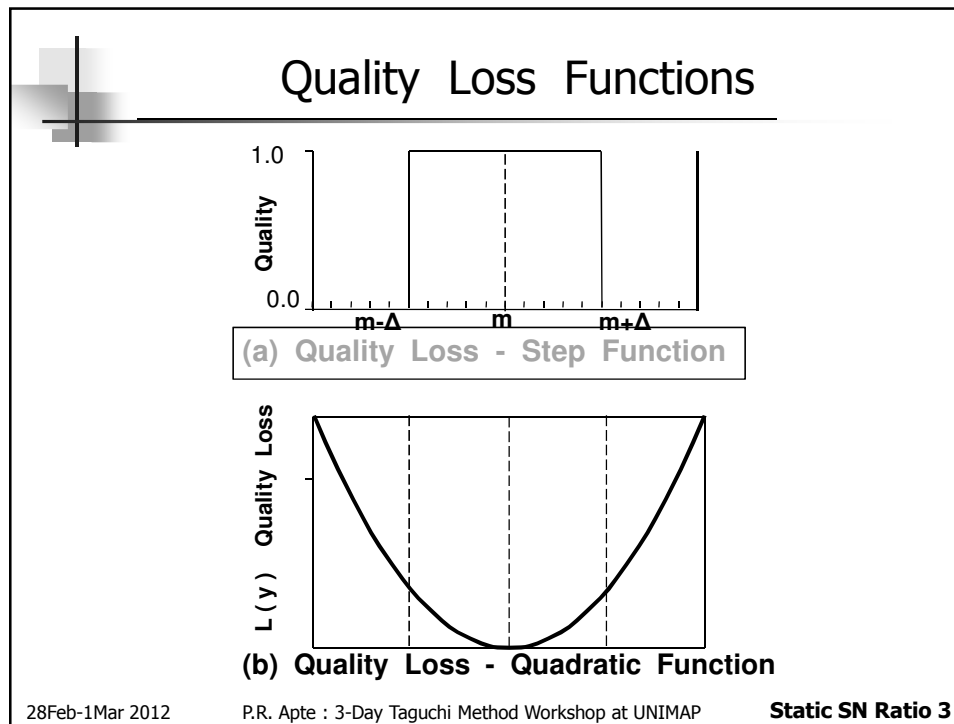


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**TAGUCHI'S CONCEPT of  
QUALITY-LOSS FUNCTION**

- **Products meeting tolerance also inflict a quality loss**
- **Best quality when performance is on target**

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### TAGUCHI'S QUADRATIC LOSS FUNCTION

- **Step Function**
  - Quality Loss  $L(y) = 0$  for  $|y - m| \leq \Delta_0$   
 $= \Delta_0$  otherwise
- **Quadratic Loss Function**
  - Quality Loss  $L(y) = k(y - m)^2$   
 where  $k$  is called the quality coefficient

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## INTERPRETATION of ENGINEERING TOLERANCES

- **Step Quality Loss Function misrepresents quality from customer's point of view**
- **Quadratic Loss Function defined by Taguchi**

$$L(y) = k(y - m)^2$$

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## AVERAGE QUALITY LOSS

- **Quadratic quality loss function measures quality loss of a single unit with quality characteristic, say, 'y<sub>1</sub>'**
- ➔ **Then Quality Loss,  $L(y_1) = k(y_1 - m)^2$**
- **For 'n' units with y<sub>1</sub>, y<sub>2</sub>, y<sub>3</sub>, .., y<sub>n</sub> the quality loss for each unit is**

$$L(Y_1) = k(Y_1 - m)^2$$

$$L(Y_2) = k(Y_2 - m)^2$$

$$L(Y_n) = k(Y_n - m)^2$$

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## AVERAGE QUALITY LOSS

- The sum of all quality losses is

$$L(Y_1) + L(Y_2) + \dots + L(Y_n) = k [(Y_1 - m)^2 + \dots + (Y_n - m)^2]$$

- Average quality loss is

$$Q_{av} = \frac{k}{n} [(Y_1 - m)^2 + \dots + (Y_n - m)^2]$$

- Finally

$$Q_{av} = k [(\mu - m)^2 + \sigma^2]$$

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## MEASURE OF QUALITY

- TOTAL LOSS TO SOCIETY DUE TO

– FUNCTIONAL VARIATIONS

– HARMFUL SIDE EFFECTS

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## TAGUCHI'S QUADRATIC LOSS FUNCTION

### REFRIGERATOR EXAMPLE

- Assume  $k = 1$ , target value  $m = -10 C$

$$Q = [ ( m - \mu )^2 + \sigma^2 ]$$

- Case 1 : mean  $\mu = -9.5 C$ , variance = .1

$$\text{Quality Loss} = 0.35 ( C )^2$$

- Case 2 : mean  $\mu = -11 C$ , variance = .2

$$\text{Quality Loss} = 1.2 ( C )^2$$

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## INTERPRETATION OF AVERAGE QUALITY LOSS

- $Q = k [ ( m - \mu )^2 + \sigma^2 ]$
- Taguchi's quality loss function is a cost function, with MONEY element contained in 'k'
- 'k' occurs as multiplication factor or 'magnification factor' of the statistical term  $[ ( m - \mu )^2 + \sigma^2 ]$
- Thus reducing  $[ ( m - \mu )^2 + \sigma^2 ]$  will reduce quality loss

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## INTERPRETATION OF AVERAGE QUALITY LOSS

- 'k' can be expressed as a product  $k_1.k_2.k_3...k_n$ 
  - $k_1$  —> Purchasing efficiency
  - $k_2$  —> Servicing efficiency
  - $k_3$  —> Administration efficiency
  - $k_4$  —> Marketing & Sales efficiency
  - $k_n$  —> Organisational efficiency
- Minimising 'k' leads to about 7% to 10% reduction in quality loss
- Reducing  $[(m - \mu)^2 + \sigma^2]$  leads to more than 70% reduction in quality loss
- Reducing  $[(m - \mu)^2 + \sigma^2]$  also reduces 'k' due to synergistic effects
- For Robust Design application we assume  $k = 1$

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## REDUCING AVERAGE QUALITY LOSS

(a) by bringing mean on target

- 
- $Q = k[(m - \mu)^2 + \sigma^2]$
  - Two terms are  $(m - \mu)^2$  and  $\sigma^2$
  - $(m - \mu)^2$  : Bring mean on target to reduce this term
  - Conventional design concentrates on on bringing mean on target

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## REDUCING AVERAGE QUALITY LOSS

### (b) by reducing variance

- $\sigma^2$ : Variance must be reduced .  
Conventional design reduces variance by screening or by tolerance design
- Robust design concentrates on reducing variance ' $\sigma^2$ ' without adding to the cost
- Finally, the mean ' $\mu$ ' is put on target 'm'

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## ROBUST DESIGN METHODOLOGY

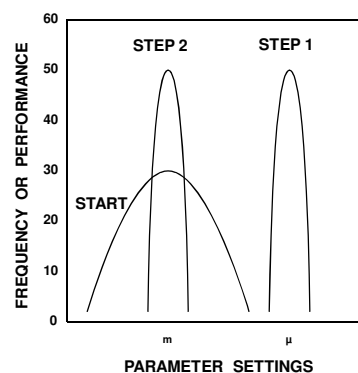
### 2 - STEP OPTIMIZATION

#### STEP 1 :

REDUCE VARIATION IRRESPECTIVE OF TARGET VALUE

#### STEP 2 :

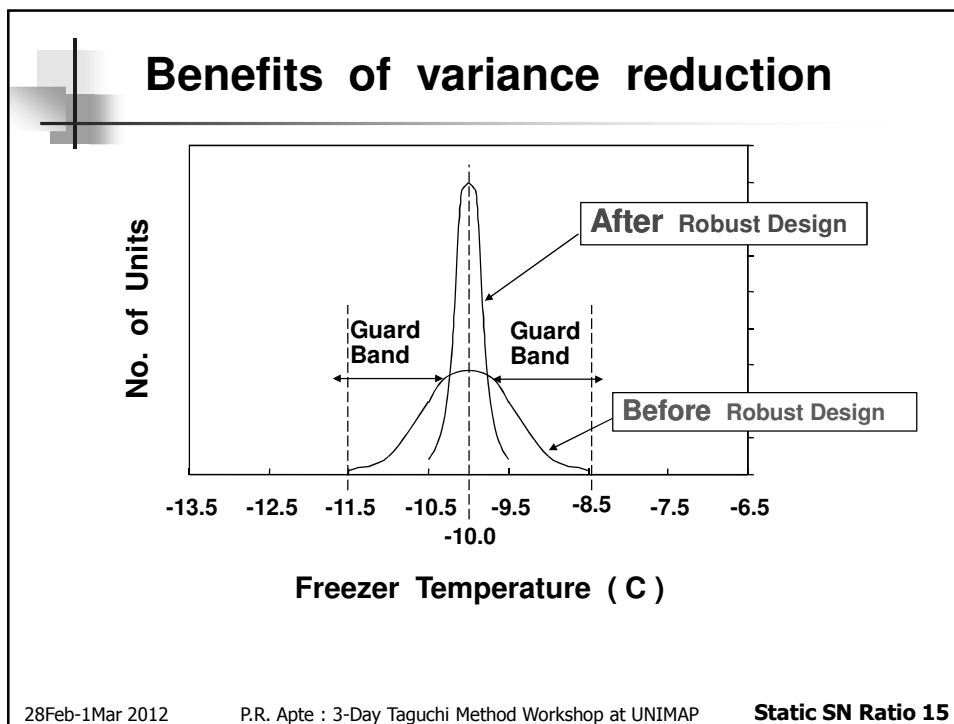
ADJUST PERFORMANCE ON TARGET LEAVING VARIATION UNDISTURBED



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### EXPLOITING NONLINEARITY

$Y = f(X, Z)$  where  $X = (x_1, x_2, \dots, x_n)$  noise factors  
 $Z = (z_1, z_2, \dots, z_m)$  control factors

- If  $\Delta x_1, \Delta x_2, \dots, \Delta x_n$  are random deviations in the noise factors (X), then each one of these causes deviations in 'y'
- If  $\Delta y$  is the sum of all the deviations due to change in the noise factors, then

$$\Delta y = \frac{\partial f}{\partial x_1} \Delta x_1 + \frac{\partial f}{\partial x_2} \Delta x_2 + \dots + \frac{\partial f}{\partial x_n} \Delta x_n$$

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## EXPLOITING NONLINEARITY

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$$\Delta y^2 = \left[ \frac{\partial f}{\partial x_1} \right]^2 \Delta x_1^2 + \left[ \frac{\partial f}{\partial x_2} \right]^2 \Delta x_2^2 + \dots + \left[ \frac{\partial f}{\partial x_n} \right]^2 \Delta x_n^2$$

$$\sigma_y^2 = \left[ \frac{\partial f}{\partial x_1} \right]^2 \sigma_{x_1}^2 + \left[ \frac{\partial f}{\partial x_2} \right]^2 \sigma_{x_2}^2 + \dots + \left[ \frac{\partial f}{\partial x_n} \right]^2 \sigma_{x_n}^2$$

- Terms are called **SENSITIVITY COEFFICIENTS**
- **Robust design reduces sensitivity coefficients by adjusting levels of control factors ( Z )**

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## Nonlinear Relationship Exploitation

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**Ambient Temperature ( C )**

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## EXAMPLES OF S / N RATIOS

### (1) Smaller - the - Better type problems

$$\eta = -10 \text{ Log}_{10} \left[ \frac{1}{n} \sum (Y_1^2 + Y_2^2 \dots + Y_n^2) \right]$$

### (2) Nominal - the - Best type problems

$$\eta = 10 \text{ Log}_{10} \left[ \frac{\mu^2}{\sigma^2} \right]$$

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## CLASSIFICATION OF DESIGN PROBLEMS

### ➤ Classification is based on type of SIGNAL factor

#### ➤ Static Problems : (Signal Factor is Constant)

- Smaller - the - Better
- Nominal - the - Best
- Larger - the - Better
- Signed Target
- Fraction Defective
- Ordered Categorical
- Curve or Vector Response

#### ➤ Dynamic Problems : (Response follows Signal)

- Continuous - Continuous (C-C)
- Continuous - Digital (C-D)
- Digital - Continuous (D-C)
- Digital - Digital (D-D)

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# Thank You

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